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INTERNATIONAL STANDARD



**Information technology – UPnP device architecture –
Part 19-10: Solar Protection Blind Device Control Protocol – Two Way Motion
Motor Service**

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CONTENTS

1	Overview and Scope.....	3
2	Service Modeling Definitions.....	3
2.1	Service Type	3
2.2	State Variables.....	4
2.2.1	OperationMode	5
2.2.2	ServiceLocked	5
2.2.3	Position	5
2.2.4	PositionArgType	5
2.2.5	Relationships between State Variables.....	6
2.3	Eventing and Moderation	6
2.4	Actions.....	6
2.4.1	(Void) Open().....	7
2.4.2	(Void) Close()	8
2.4.3	(Void) Stop().....	9
2.4.4	(String) GetOperationMode(RetVal).....	10
2.4.5	(Void) SetOperationMode(String)	10
2.4.6	(Void) IsLocked(Boolean).....	11
2.4.7	(Void) Lock().....	11
2.4.8	(Void) UnLock()	12
2.4.9	(Float) GetPosition(RetVal)	13
2.4.10	(Void) SetPosition(I1).....	13
2.4.11	(String) GetPositionArgType(RetVal).....	14
2.4.12	Non-Standard Actions Implemented by a UPnP Vendor	15
2.4.13	Relationships between Actions.....	15
2.4.14	Common Error Codes	15
2.5	Theory of Operation.....	15
3	XML Service Description	17
4	Test	20
	Table 1: State Variables	4
	Table 1.1: allowedValueList for <u>OperationMode</u>	4
	Table 1.2: DefaultValue for <u>OperationMode</u>	4
	Table 1.5: allowedValueRange for <u>Position</u>	4
	Table 1.6: DefaultValue for <u>Position</u>	4
	Table 1.7: allowedValueList for <u>PositionArgType</u>	5
	Table 1.8: DefaultValue for <u>PositionArgType</u>	5
	Table 2: Event Moderation	6
	Table 3: Actions.....	7
	Table 4.1: Arguments for <u>Open</u>	7
	Table 4.2: Arguments for <u>Close</u>	8
	Table 4.3: Arguments for <u>Stop</u>	9

Table 4.4: Arguments for <u>GetOperationMode</u>	10
Table 4.5: Arguments for <u>SetOperationMode</u>	10
Table 4.6: Arguments for <u>IsLocked</u>	11
Table 4.7: Arguments for <u>Lock</u>	11
Table 4.8: Arguments for <u>UnLock</u>	12
Table 4.9: Arguments for <u>GetPosition</u>	13
Table 4.10: Arguments for <u>SetPosition</u>	13
Table 4.11: Arguments for <u>GetPositionArgType</u>	14
Table 5: Common Error Codes	15

INFORMATION TECHNOLOGY – UPnP DEVICE ARCHITECTURE –

Part 19-10: Solar Protection Blind Device Control Protocol – Two Way Motion Motor Service

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This International Standard has been approved by vote of the member bodies, and the voting results may be obtained from the address given on the second title page.

¹ UPnP Forum Steering committee, UPnP Forum, 3855 SW 153rd Drive, Beaverton, Oregon 97006 USA. See also "Introduction".

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1 Overview and Scope

This service definition is compliant with the UPnP Device Architecture version 1.0.

This service-type enables the following functions:

- Driving a motor between two fixed end limits.
- Reaching any position written in percentage of the full run (optional).
- Returning the actual blind position written in percentage of the full run (optional).

This service template does not address:

- Any motorization whose run is not bounded.
- Any speed control.